

assumptions:

$$c_t: S \rightarrow \mathbb{R} \quad c_t(x) \in [-c, c]$$

$$B \in S \subset \mathbb{R}^B$$

c_t 's are L -Lipschitz

$$|c_t(x) - c_t(y)| \leq L|x - y|$$

Lecture 22

Alg: $y_1 = 0$

at each period t

select uniform, random unit vector u_t

$$x_t = y_t + \delta u_t$$

"play" x_t & observe $c_t(x_t)$

$$y_{t+1} = \frac{\rho}{1-\rho} S \left(y_t - \rho c_t(x_t) u_t \right)$$

$$E_{u \in S} \left[\frac{d}{\delta} \cdot f(x + \delta u) u \right] = \nabla \hat{f}(x)$$

$$\hat{f}(x) = E_{v \in B} [f(x + \delta v)] \text{ - smoothed } f.$$

$$E \left[\sum_{t=1}^n c_t(z_t) \right] - \min_{x \in S} \sum_{t=1}^n c_t(x) \leq R G \sqrt{n}$$

where $z_1 = 0$
 $z_{t+1} = P_S(z_t - \eta g_t)$ $\eta = \frac{R}{G \sqrt{n}}$

$$E[g_t | z_t] = \nabla c_t(z_t)$$

$$\|g_t\| \leq G$$

$$S \subset \mathbb{R}^B$$

radius of S .

"min in $(1-\alpha)S$ is close to min in S ."

(*) Lemma: $\min_{x \in (1-\alpha)S} \sum_{t=1}^n c_t(x) \leq 2\alpha Cn + \min_{x \in S} \sum_{t=1}^n c_t(x)$

pt. $x \in S \Rightarrow (1-\alpha)x \in (1-\alpha)S$

$$c_t((1-\alpha)x) \leq (1-\alpha)c_t(x) + \alpha c_t(0)$$

$$\leq c_t(x) + \underbrace{2\alpha C}$$

since $|c_t(x)|, |c_t(0)| \leq C$

• Sum over n periods; substitute x^* for x

$$x^* = \operatorname{argmin}_{x \in S} \sum_{t=1}^n c_t(x)$$

$$\min_{x \in (1-\alpha)S} \sum_{t=1}^n c_t(x) \leq \sum_{t=1}^n c_t((1-\alpha)x^*) \leq 2\alpha Cn + \sum_{t=1}^n c_t(x^*)$$

(**) Lemma: $\forall x \in (1-\alpha)S$ the ball of radius

αr centered at x is contained in S

pt. $S = (1-\alpha)S + \alpha S$

$$\Rightarrow \forall x \in S \Rightarrow \exists y \in (1-\alpha)S, z \in \alpha S \text{ s.t.}$$

$$x = y + z$$

$$y = (1-\alpha)x \quad z = \alpha x.$$

$$\Leftarrow \forall y \in (1-\alpha)S, z \in \alpha S \Rightarrow \exists x \in S \text{ s.t.}$$

$$x = y + z.$$

$$\begin{cases} \hat{y} \in S \text{ s.t. } (1-\alpha)\hat{y} = y \\ \hat{z} \in S \text{ s.t. } \alpha\hat{z} = z \end{cases} \quad (1-\alpha)\hat{y} + \alpha\hat{z} \in S$$

since S is convex.

$$S = (1-\alpha)S + \alpha S \geq (1-\alpha)S + \alpha r B$$

since $rB \in S$.

Thm. for $n \geq \left(\frac{3Rd}{2r}\right)^2$ and for $v = \frac{R}{c\sqrt{n}}$

$$\delta = \sqrt{\frac{rR^2 d^2 c}{12n}}$$

$$\alpha = \sqrt[3]{\frac{3Rd}{2r\sqrt{n}}}$$

the expected regret of Alg is bounded by.

Thm. If each c_t is L -Lipschitz, for n sufficiently large and $v = \frac{R}{c\sqrt{n}}$, $\alpha = \frac{\delta}{r}$.

and $\delta = n^{-\frac{1}{4}} \sqrt{\frac{RdCr}{3(Lr+C)}}$

then expected regret of Alg is bounded by

$$2n^{3/4} \sqrt{3RdC(L+C/r)}$$

ph • begin by showing each $x_t \in S$.

• $y_t \in (1-\alpha)S$ by lemma (***) know that

• if $\delta \leq \alpha r$ we are good.

• we set $\alpha = \frac{\delta}{r} \Rightarrow \delta = \alpha r$.

- Let $\hat{c}_t(x)$ be the smoothed version of $c_t(x)$.

- We first show a good regret result using the \hat{c} 's y_t 's then we show that using the original c 's x_t 's can't hurt the result too much.

- Let $\hat{c}_t(x) = E_{v \in B} [c_t(x + \delta v)]$

- Let the feasible region be $(1-\alpha)S$.

- Let $g_t = \frac{d}{\delta} c_t(y_t + \delta u_t) u_t$.

- By estimate lemma. $E[g_t | y_t] = \nabla \hat{c}_t(y_t)$

- So we can apply exp. gradient descent rules

$$y_{t+1} = P_{(1-\alpha)S} (y_t - \eta g_t)$$

$$y_{t+1} = P_{(1-\alpha)S} \left(y_t - \underbrace{\eta \frac{d}{\delta}}_{\text{step size } \eta} c_t(y_t + \delta u_t) u_t \right)$$

step size η .

but otherwise, same rule as we use

$$\|g_t\| = \left\| \frac{d}{\delta} c_t(y_t + \delta u_t) u_t \right\| \leq \frac{d}{\delta} C = "G"$$

$$\frac{R}{C\sqrt{n}} = \eta \frac{d}{\delta} \Rightarrow \eta = \frac{\delta R}{d C \sqrt{n}} = \frac{R}{G \sqrt{n}}$$

• so, exp grad lemma tells us.

$$E \left[\sum_{t=1}^n \hat{c}_t(y_t) \right] - \min_{x \in (1-\alpha)S} \sum_{t=1}^n \hat{c}_t(x) \leq R G \sqrt{n} \\ = \frac{R d C \sqrt{n}}{\delta}$$

ok, so now we have to get rid of the \hat{c}_t 's y_t 's. $(1-\alpha)S$.

Let's think about switching from \hat{c}_t to c_t .

$$|\hat{c}_t(x) - c_t(x)| = \left| \int_{\mathcal{V}} p(v) c_t(x + \delta v) - \int_{\mathcal{V}} p(v) c_t(x) \right|$$

$$= \left| \int_{\mathcal{V}} p(v) [c_t(x + \delta v) - c_t(x)] \right|$$

$$\leq \int_{\mathcal{V}} p(v) |c_t(x + \delta v) - c_t(x)|$$

$$\leq \int_{\mathcal{V}} p(v) \delta L \quad \leftarrow \text{since } c_t \text{'s are } L\text{-Lipschitz.}$$

$$= \delta L$$

$$|\hat{c}_t(x) - c_t(x)| \leq \delta L$$

• But we also want to go from y 's to x 's.

$$\begin{aligned} |\hat{c}_+(y_t) - c_+(x_t)| &\leq |\hat{c}_+(y_t) + c_+(y_t) - c_+(y_t) - c_+(x_t)| \\ &\leq |\hat{c}_+(y_t) - c_+(y_t)| + |c_+(y_t) - c_+(x_t)| \\ &\leq \delta L + \delta L, \text{ since } x_t = y_t + \delta u_t \\ &= 2\delta L \end{aligned}$$

• great! all we have left is the $(1-\alpha)S$.

$$\begin{aligned} E \left[\sum_{t=1}^n (c_+(x_t) - 2\delta L) \right] &= \min_{x \in (1-\alpha)S} \sum_{t=1}^n (c_+(x) + \delta L) \\ &\leq \frac{RdC\sqrt{n}}{\delta} \end{aligned}$$

but we know that the mins are close by Lemma (*), so

$$\begin{aligned} E \left[\sum_{t=1}^n c_+(x_t) \right] &= \min_{x \in S} \sum_{t=1}^n c_+(x) - 2\alpha Cn \\ &\leq \frac{RdC\sqrt{n}}{\delta} + 3\delta Ln \end{aligned}$$

or regret bound by

$$\begin{aligned} &\frac{RdC\sqrt{n}}{\delta} + 2\alpha Cn + 3\delta Ln \\ &= \frac{RdC\sqrt{n}}{\delta} + \frac{2\delta Cn}{r} + 3\delta Ln \end{aligned}$$

plugin $\delta \propto n^{-1/4}$ gives me regret $\propto n^{3/4}$. □